

# Shih Kang Chiu

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Developer ~ Engineer

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## SUMMARY

My research area focuses on Human-Computer Interaction (HCI). I apply my expertise specifically in advanced haptic feedback for AR/VR applications and granting novel properties to enhance user experience, for short, I engineer custom-made interactive devices.

My graduation thesis has centered on leveraging user-in-the-loop LLM to enhance real-time note-taking in mobile settings using AR headset and eye-tracking technique.

I have extensive experience in Unity development. In addition to 2D and 3D games, I also have experience with VR games and applications (including Vive, Oculus, and Hololens).

I participated in various competitions and industry-academia collaborations, received multiple scholarships, and maintained well academic performance. For detailed project information, please visit my personal website.

## SKILLS

**Languages:** C#, Python, JavaScript

**Technologies:** Unity, Arduino, Fusion 360, Blender

## EDUCATION

8/2022 | Department of Computer Science | MSc  
7/2024 | National Chengchi University  
Avg 91.41 / GPA 4.30

9/2014 | Department of International Business | BBA  
7/2018 | National Chengchi University

## PUBLICATIONS

Graduation Thesis **GazeNoter: Co-Piloted AR Note-Taking via Gaze Selection of LLM Suggestions to Match Users' Intentions.**  
**Shih-Kang Chiu**, Bryan Wang, Hsin-Ruey Tsai  
*Under review*

HCI / LLM / AR

Publication **transPAF: Rendering Omnidirectional Impact Feedback with Dynamic Point of Application of Force All Round a Controller.**  
Hong-Xian Chen, **Shih-Kang Chiu**, Chi-Ching Wen, Hsin-Ruey Tsai  
*Proceedings of the ACM Conference on Human Factors in Computing Systems (CHI' 23)*

HCI / VR / Haptic feedback

Thesis **Prop Revolver: A forearm-worn device renders changeable props with manipulation and force feedback in XR.**  
Wei-Lin Hsu, **Shih-Kang Chiu**, Hsin-Ruey Tsai  
*Under review*

HCI / VR / Haptic feedback

## PROJECTS

1/2024 | **Delta x NTU: User-in-the-loop AI and XR Combined Human-Robot Collaboration** | Industry cooperation  
7/2024 |  
• PI: Robin Bing-Yu Chen Co-PI: Hsin-Ruey Tsai  
• Incorporating user engagement in AI and XR combined human-robot collaboration and delves into the complexities of interacting with multiple robots, various input modalities, and diverse commanding methodologies.  
HRI / LLM / VLM

9/2023 | **Freeperson: The Digital-Twins Machine** | Digital content exhibition  
8/2022 |  
• PI: Tao Ya-Lun  
• A interactive exhibition connecting two physical spaces by creating a co-located digital body of the user using an autonomous robot, a wearable prop device, and XR headset.  
HRI / Haptic feedback / Immersive design

## HONOURS & AWARDS

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- 2023      **Academic Paper Award - College of Informatics, Academic Year 111**
- Scholarship holder
- 2023      **NIICC The National Collegiate Innovation Integration Competition**
- Honorable Mention
  - We propose transPAF, a controller that could render omnidirectional impact feedback with dynamic Point of Application of Force (PAF) all around the controller.
- 2024      **Outstanding Competition Achievement Award - College of Informatics, Academic Year 113**
- Scholarship holder
- 2024      **Mobileheroes Global**
- Top 10 (final round and ongoing )
  - We propose GazeNoter which pioneers a user-in-the-loop LLM and AR technology to achieve real-time note-taking during speech-based activity.

## TEACHING ASSISTANT EXPERIENCE

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2022-Fall	<b>Virtual Reality Haptic Interactions</b>	<b>Computer Science</b>
2023-Spring	<b>Interaction Technologies Research and Discussion</b>	<b>Computer Science</b>
2023-Spring	<b>Implementation of Digital Content and Technologies</b>	<b>Digital Content and Technologie</b>
2023-Fall	<b>Introduction to Digital Contents and Technologies</b>	<b>Digital Content and Technologie</b>
2024-Spring	<b>Implementation of Digital Content and Technologies</b>	<b>Digital Content and Technologie</b>
2024-Spring	<b>Special Projects on Digital Content and Technology</b>	<b>Digital Content and Technologie</b>

## LANGUAGES

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**Chinese** - native, **English** - fluent (TOEIC 910)